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(11)

EP 0 844 129 A3

(12)

EUROPEAN PATENT APPLICATION

(88) Date of publication A3:
07.07.1999 Bulletin 1999/27

(51) Int. Cl.⁶: B60K 23/00, B60K 17/00

(43) Date of publication A2:
27.05.1998 Bulletin 1998/22

(21) Application number: 97119744.7

(22) Date of filing: 11.11.1997

(84) Designated Contracting States:
AT BE CH DE DK ES FI FR GB GR IE IT LI LU MC
NL PT SE
Designated Extension States:
AL LT LV MK RO SI

(30) Priority: 13.11.1996 JP 30151996
13.11.1996 JP 30152096

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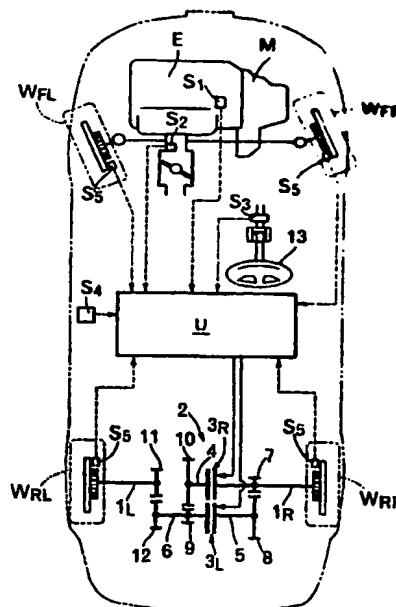
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(54) Yaw moment control system in vehicle

(57) A yaw moment control system is provided to eliminate an under-steering tendency generated due to the insufficiency of a cornering force of front driven wheels of a vehicle. More specifically, in place of a longitudinal acceleration X_g and a lateral acceleration Y_g used for calculating the amount of torque distributed, a corrected longitudinal acceleration X_g' larger than the value directly proportional to the longitudinal acceleration X_g and a corrected lateral acceleration Y_g' larger than the value directly proportional to the lateral acceleration Y_g are used, thereby increasing the amount of torque distributed to between inner and outer wheels during turning of the vehicle. A yaw moment is generated which is directed inwards in the turning direction to prevent the under-steering tendency which is generated due to the insufficiency of the cornering force of the front wheels.

FIG. 1



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FIG.5A

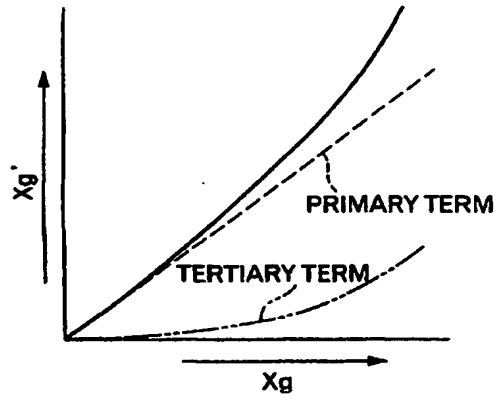
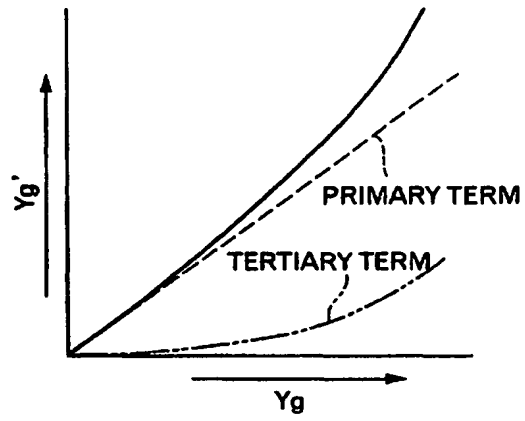


FIG.5B





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EUROPEAN SEARCH REPORT

Application Number
EP 97 11 9744

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The present search report has been drawn up for all claims			
Place of search THE HAGUE		Date of completion of the search 10 May 1999	Examiner Goeman, F
CATEGORY OF CITED DOCUMENTS X : particularly relevant if taken alone Y : particularly relevant if combined with another document of the same category A : technological background O : non-written disclosure P : intermediate document		T : theory or principle underlying the invention E : earlier patent document, but published on, or after the filing date D : document cited in the application L : document cited for other reasons & : member of the same patent family, corresponding document	

EPO FORM 1503 03 02 (P04C01)

**ANNEX TO THE EUROPEAN SEARCH REPORT
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